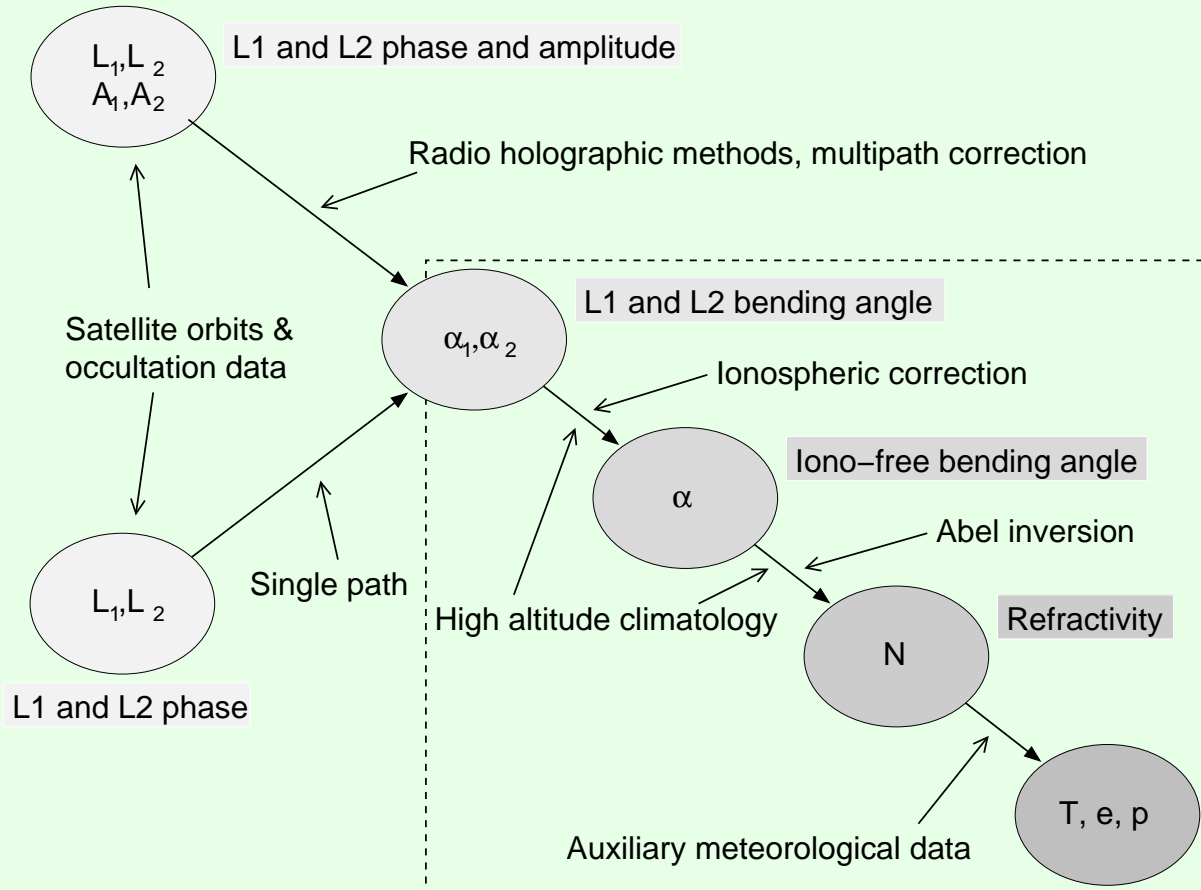


# Generic Processing of GPS RO and Microwave Occultations

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# GPS RO measurements & processing



# Bending angle $\rightarrow$ refractivity

$$\alpha(a)$$



Abel integral transform (e.g., Fjeldbo 1971)

$$\alpha(a) = -2a \int_{r_0}^{\infty} \frac{d \ln n / dr}{\sqrt{n^2 r^2 - a^2}} dr \quad \Leftrightarrow \quad n(r_0) = \exp \left( \frac{1}{\pi} \int_a^{\infty} \frac{\alpha(x)}{\sqrt{x^2 - a^2}} dx \right)$$

$$r_0 = \frac{a}{n(r_0)} \quad , \quad N(r_0) = 10^6 \times (n(r_0) - 1)$$



$$N(r)$$

- The Abel integral transform relies on the assumption of spherical symmetry
- It provides a simple and unique solution to an otherwise under-determined inverse problem
- A few issues: 1) ionospheric correction; 2) statistical optimization – how to handle the upper boundary

# Ionospheric correction of bending angles

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The ionosphere-free bending angle is formed from the derived bending angles at the same impact parameter (Vorob'ev and Krasil'nikova 1994):

$$\alpha(a) = \frac{f_1^2 \alpha_1(a) - f_2^2 \alpha_2(a)}{f_1^2 - f_2^2}$$

- In practice one has to consider filtering of small-scale ionospheric residuals and excessive L2 noise (Sokolovskiy, 2009)
- The GRAS SAF uses a so-called optimal linear combination approach (Gorbunov, 2002), combining ionospheric correction and statistical optimization in a Bayesian framework

# Statistical optimization



- Formally, we need bending angles to infinite altitudes in order to derive the refractivity (of course we don't have that)
- Bending angles are contaminated with thermal noise and residual noise from ionospheric turbulence
- Fractionally the noise increases exponentially with altitude rendering the bending angle useless at some altitude and above

Optimal estimation of bending angle:

$$\tilde{\alpha}(a) = \alpha_{\text{bg}}(a) + \frac{\sigma_{\text{bg}}^2}{\sigma_{\text{bg}}^2 + \sigma_{\text{obs}}^2} [\alpha(a) - \alpha_{\text{bg}}(a)]$$

$\alpha_{\text{bg}}$  is estimated from a climatological model or other

$\sigma_{\text{obs}}$  may be evaluated from the data above the stratosphere

$\sigma_{\text{bg}}$  may be fixed (e.g., 20%) or estimated

# The GRAS SAF approach



- Based on a spectral representation of the MSIS climatological model transformed to bending angle space
- Global search in model space + scaling and offset (Gobiet and Kirchengast, 2004; Lohmann, 2005)
- Least squares fit of  $A\alpha_{\text{gmsis}}^B$  to the observed (non-optimized) bending angle between 40 and 60 km, and then...

$$\min[(\ln A)^2 + (B - 1)^2]_{\text{global search}} \Rightarrow \alpha_{\text{bg}} = A\alpha_{\text{gmsis}}^B$$

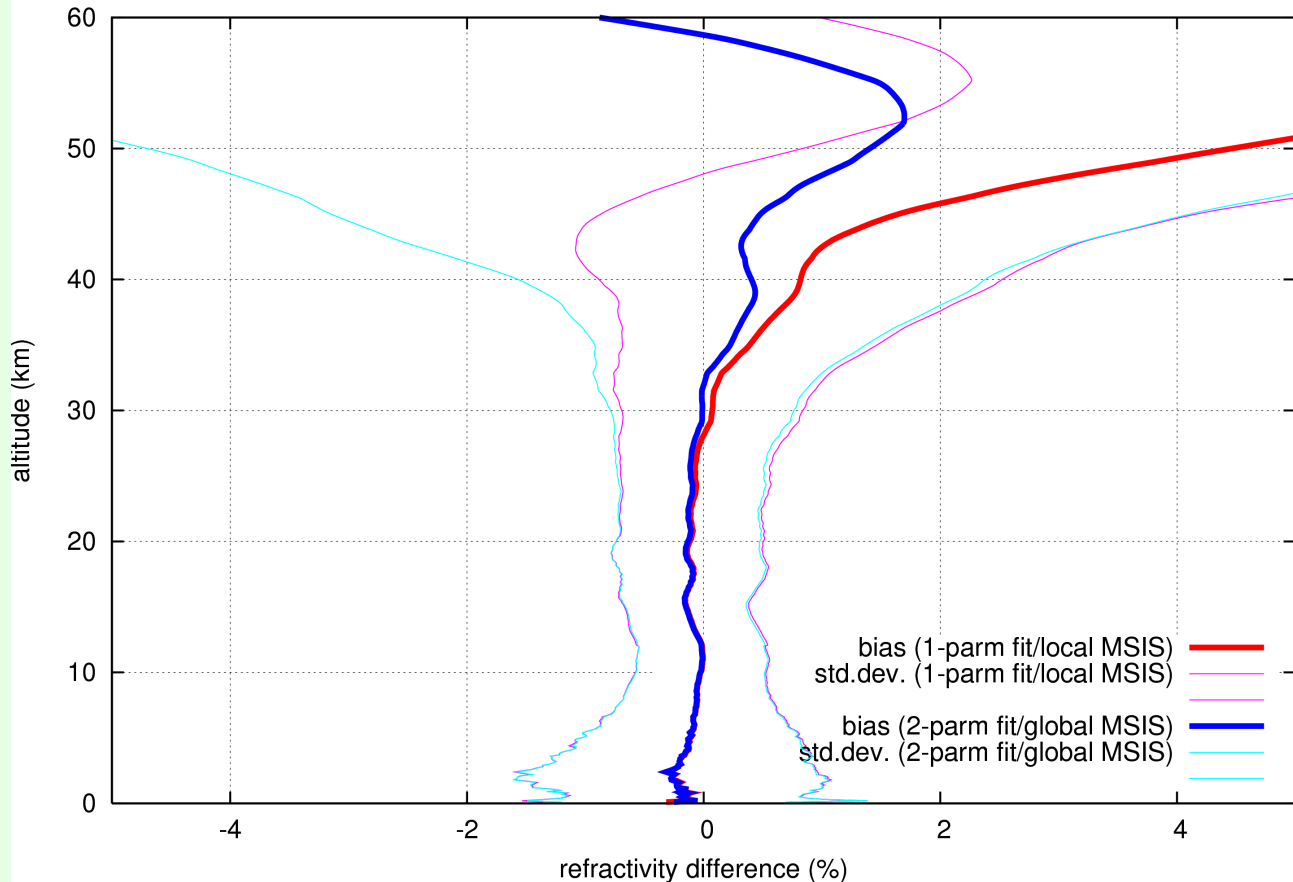
Optimal linear combination:

$$\begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = \mathbf{K} \begin{pmatrix} \tilde{\alpha} \\ \Delta\alpha_{\text{I}} \end{pmatrix}, \quad \mathbf{K} = \begin{pmatrix} 1 & f_2^2/(f_1^2 - f_2^2) \\ 1 & f_1^2/(f_1^2 - f_2^2) \end{pmatrix}$$

$$\begin{pmatrix} \tilde{\alpha} \\ \Delta\alpha_{\text{I}} \end{pmatrix} = \begin{pmatrix} \alpha_{\text{bg}} \\ \langle \Delta\alpha_{\text{I}} \rangle \end{pmatrix} + \mathbf{K}^\dagger \begin{pmatrix} \alpha_1 - \alpha_{\text{bg}} - \langle \Delta\alpha_{\text{I}} \rangle f_2^2/(f_1^2 - f_2^2) \\ \alpha_2 - \alpha_{\text{bg}} - \langle \Delta\alpha_{\text{I}} \rangle f_1^2/(f_1^2 - f_2^2) \end{pmatrix}$$

# Refractivity statistics against ECMWF

First ten days of April, 2009 (observations - ECMWF forecasts)



# Refractivity $\rightarrow$ pressure & temperature



Refractivity equation:

$$N \approx 77.6 \frac{p}{T} + 3.73 \times 10^5 \frac{e}{T^2}$$

- Two terms: a dry (or hydrostatic) term and a wet term
- The wet term can be neglected at temperatures less than  $\sim 240$  K (i.e., at few kilometers above the surface at high latitudes and above  $\sim 10$  km at tropical latitudes)

Neglecting the wet term:

$$N(r) \rightarrow \left[ \begin{array}{l} N = 77.6 \frac{p}{T} \quad , \quad p = \rho R_d T \\ \frac{dp}{dz} = -\rho g \quad , \quad z = r - r_{\text{curv}} \end{array} \right] \rightarrow p(z), T(z)$$



# Deriving temperature and water vapor



1. Include additional information about the actual temperature profile and solve directly for water vapor (iterative procedure)
2. One-dimensional variational technique optimally combining the refractivity profile with information from an NWP model
3. The 'COSMIC approach'

Method number 1:

$$N(z), T_{\text{apriori}}(z)$$



$$e = T^2 \frac{N - 77.6(p_d + e)/T}{3.73 \times 10^5}, \quad \frac{d(p_d + e)}{dz} = -(\rho_d + \rho_w)g$$
$$p_d = \rho_d R_d T, \quad e = \rho_w R_w T$$



$$e(z), p_d(z)$$

# An optimal solution toward $T$ , $p$ , and $e$



Method number 2 (variational retrieval):

- Include information about errors in a priori temperature, pressure and water vapor, as well as errors in the observed refractivity

$$N(z), T_{\text{apriori}}(z), p_{\text{apriori}}(z), e_{\text{apriori}}(z)$$



Minimizing the following cost function:

$$J(\mathbf{x}) = (\mathbf{x} - \mathbf{x}_b)^T \mathbf{B}^{-1} (\mathbf{x} - \mathbf{x}_b) + (\mathbf{N}_{\text{obs}} - \mathbf{N}(\mathbf{x}))^T \mathbf{R}^{-1} (\mathbf{N}_{\text{obs}} - \mathbf{N}(\mathbf{x}))$$

$\mathbf{x}$  is the state vector to be solved for

$\mathbf{x}_b$  is the a priori state vector

$\mathbf{N}(\mathbf{x})$  is the refractivity equation

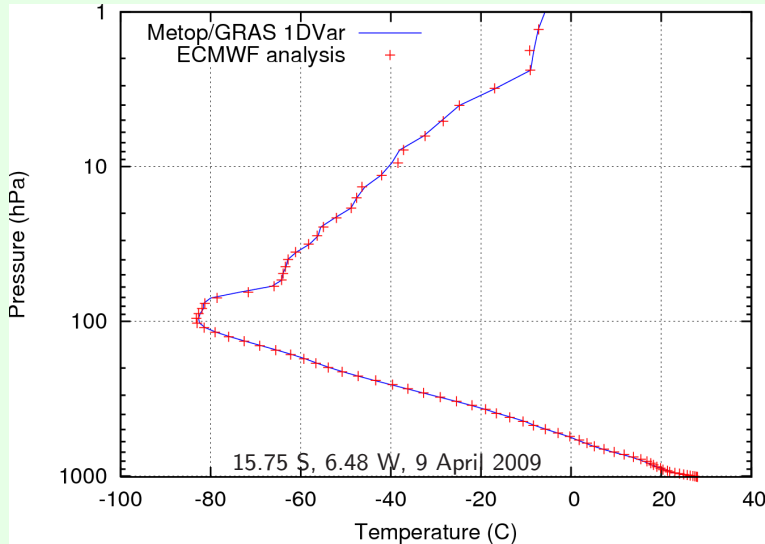
$\mathbf{B}$  is the a priori error covariance matrix

$\mathbf{R}$  is the observation + representativeness error covariance matrix



$$T(z), p(z), e(z)$$

# The GRAS SAF approach

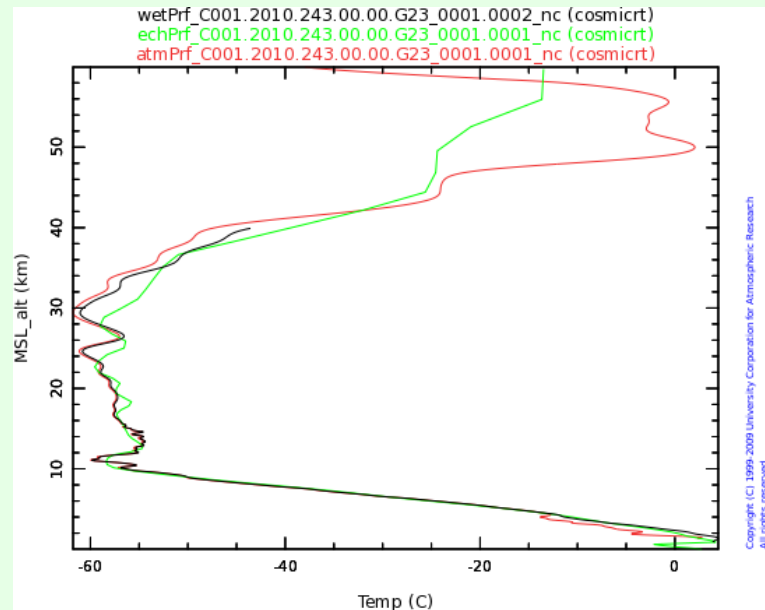


- Observations and forecast weighted according to their error covariance
- An optimal mixture between model and observation
- One disadvantage: retrieved temperature and water vapor inconsistent with observed refractivity

# The COSMIC approach

Method number 3 (COSMIC approach):

- Gives much more weight to the observations
- Seeks to minimize the influence from NWP fields, but still separate out temperature and water vapor
- Solution (almost) consistent with observed refractivity
- Retrieved temperature (almost) in-line with dry temperature where water vapor is insignificant
- Observed small-scale structure is preserved in the solution



# A similar alternative – taking the full step

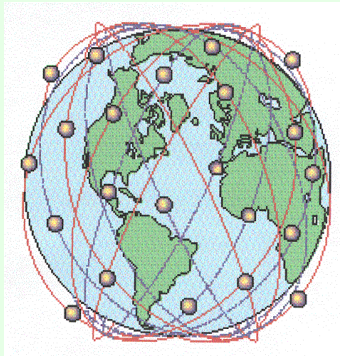
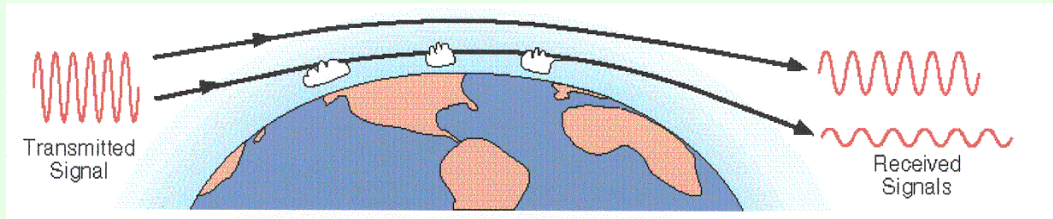
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- Give full weight to the observations (zero error;  $\mathbf{S}_O = 0$ )
- Solution fully consistent with observed refractivity ( $N_{\text{sol}} = N_{\text{obs}}$ )
- Retrieved temperature fully in-line with dry temperature where water vapor is insignificant ( $T_{\text{sol}} = T_{\text{dry}}$  where  $e = 0$ )
- Information content from observation fully preserved
- NWP model add only information on the relative contributions of dry and wet terms, based on its representation of these variables ( $\mathbf{x}_B$ ) and their error co-variances ( $\mathbf{S}_B$ )
- NWP *analyses* (where the specific RO profile presumably has already been assimilated) can be used as  $\mathbf{x}_B$  without including the information from the RO data twice (since the RO in itself does not contain information about the relative contributions of dry and wet terms)

Standard 1Dvar:  $\mathbf{x} = \mathbf{x}_B + \mathbf{S}_B \mathbf{K}^T (\mathbf{K} \mathbf{S}_B \mathbf{K}^T + \mathbf{S}_O)^{-1} (\mathbf{y} - \mathbf{K} \mathbf{x}_B)$  [notation after Rodgers (2000)]

Alternative:  $\mathbf{x} = \mathbf{x}_B + \mathbf{S}_B \mathbf{K}^T (\mathbf{K} \mathbf{S}_B \mathbf{K}^T)^{-1} (\mathbf{y} - \mathbf{K} \mathbf{x}_B) = \mathbf{x}_A + \mathbf{S}_A \mathbf{K}^T (\mathbf{K} \mathbf{S}_A \mathbf{K}^T)^{-1} (\mathbf{y} - \mathbf{K} \mathbf{x}_A)$

# Microwave occultations



Atmospheric limb sounding (occultations) using multi-frequency signals between LEO satellites

## Observations:

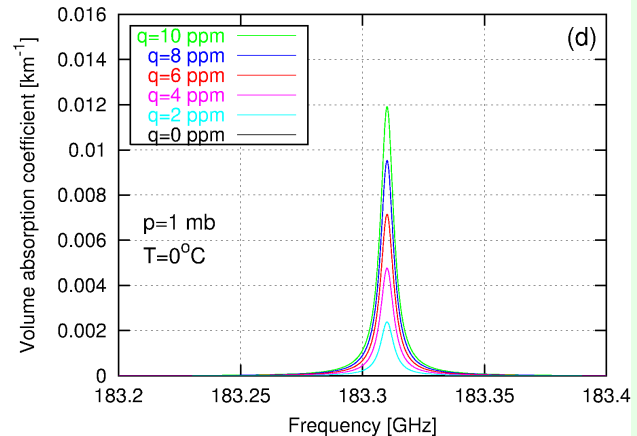
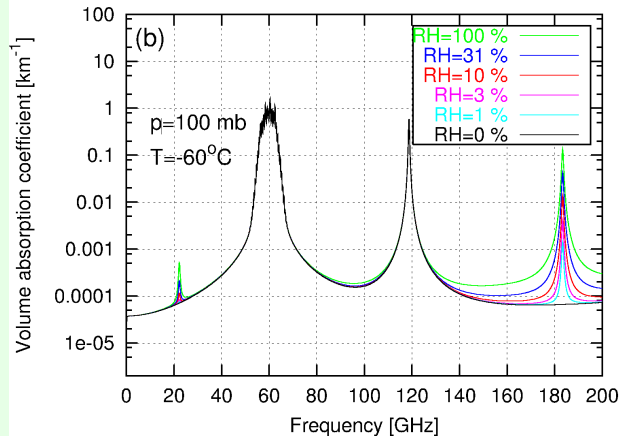
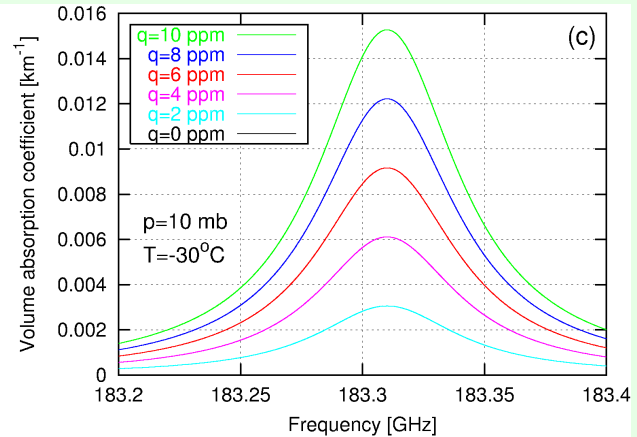
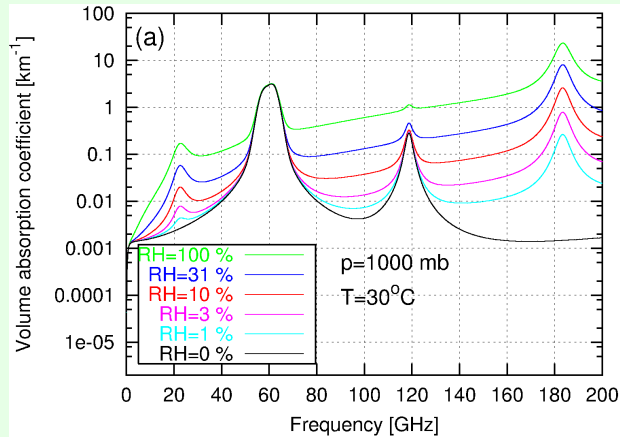
1. Refraction (via phase measurements)
2. Absorption (via amplitude measurements)

**Products:** Profiles of temperature, pressure, water vapor, ozone, ...

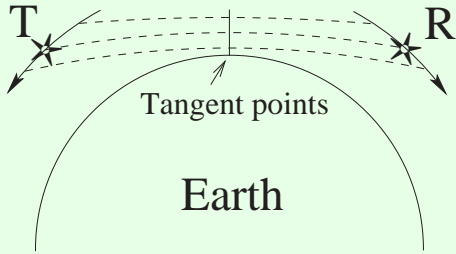
## Frequencies:

- 9-32 GHz and 178-183 GHz for moisture sounding
- 184-196 GHz for ozone sounding

# Absorption spectra below 200 GHz



# Basic principles of the observations



Optical path:

$$L = \int n ds$$

Optical depth:

$$\tau = \int k ds$$

$n$  is the real part of the refractive index

$k$  is the volume absorption coefficient (related to the imaginary part of the refractive index)

Normalized intensity:  $I/I_0 = \zeta \exp(-\tau)$

The difference in optical depth,  $\Delta\tau$ , between two signals (at two different frequencies) is obtained by signal intensity ratioing



# Basic principles of the retrieval

- Inversion to obtain  $n$  and  $\Delta k$

$$\begin{array}{l} L(t) \rightarrow \alpha(a) \rightarrow \\ I(t) \rightarrow \Delta\tau(a) \rightarrow \end{array} \quad \boxed{\begin{array}{l} n(r) = \exp\left(\frac{1}{\pi} \int_a^\infty \frac{\alpha(x)}{\sqrt{x^2 - a^2}} dx\right) \\ \Delta k(r) = -\frac{1}{\pi} \frac{da}{dr} \int_a^\infty \frac{d\Delta\tau/dx}{\sqrt{x^2 - a^2}} dx \\ a = rn(r) \end{array}} \quad \begin{array}{l} \rightarrow n(r) \\ \rightarrow \Delta k(r) \end{array}$$

- Solving a set of non-linear equations to obtain profiles of  $p$ ,  $e$ ,  $T$

$$\Delta k = F_1(p, e, T) \quad n = F_2(p, e, T) \quad dp/dz = F_3(p, e, T)$$

# Handling the integration to infinity



- Extending the bending angle profile; e.g., log-linear extrapolation to infinity
- Integration to some high altitude where the bending angle can be neglected (above 100 km)
- Analytical (approximate) expression assuming log-linear bending angle above  $a_{\text{top}}$ :

$$\int_a^\infty \frac{\alpha(x)dx}{\sqrt{x^2 - a^2}} \approx \int_a^{a_{\text{top}}} \frac{\alpha(x)dx}{\sqrt{x^2 - a^2}} + \frac{\alpha(a_{\text{top}})\sqrt{\pi H}}{\sqrt{a_{\text{top}} + a}} \exp\left(\frac{a_{\text{top}} - a}{H}\right) \operatorname{erfc}\left(\sqrt{\frac{a_{\text{top}} - a}{H}}\right)$$

- An old idea of mine: Use background/climatological bending angle defined to arbitrary high altitude (spectral representation) and apply substitution ( $x = \sqrt{a^2 + (c \ln y)^2}$ ) to effectively integrate to infinity:

$$\int_a^\infty \frac{\alpha(x)dx}{\sqrt{x^2 - a^2}} = c \int_0^1 \frac{\alpha(y)}{xy} dy$$

# ... and the lower limit



We rarely talk about it, but we all do something:

- $x = \sqrt{a^2 + (c \ln y)^2} \Rightarrow \int_a^\infty \frac{\alpha(x) dx}{\sqrt{x^2 - a^2}} = c \int_0^1 \frac{\alpha(y)}{xy} dy \quad , \quad \frac{\alpha(y)}{xy} \Big|_{y \rightarrow 0} \rightarrow 0$

- $\alpha(x) = Ax + B \Rightarrow \int_a^b \frac{\alpha(x) dx}{\sqrt{x^2 - a^2}} = A\sqrt{b^2 - a^2} + B \ln\left(\frac{b + \sqrt{b^2 - a^2}}{a}\right)$

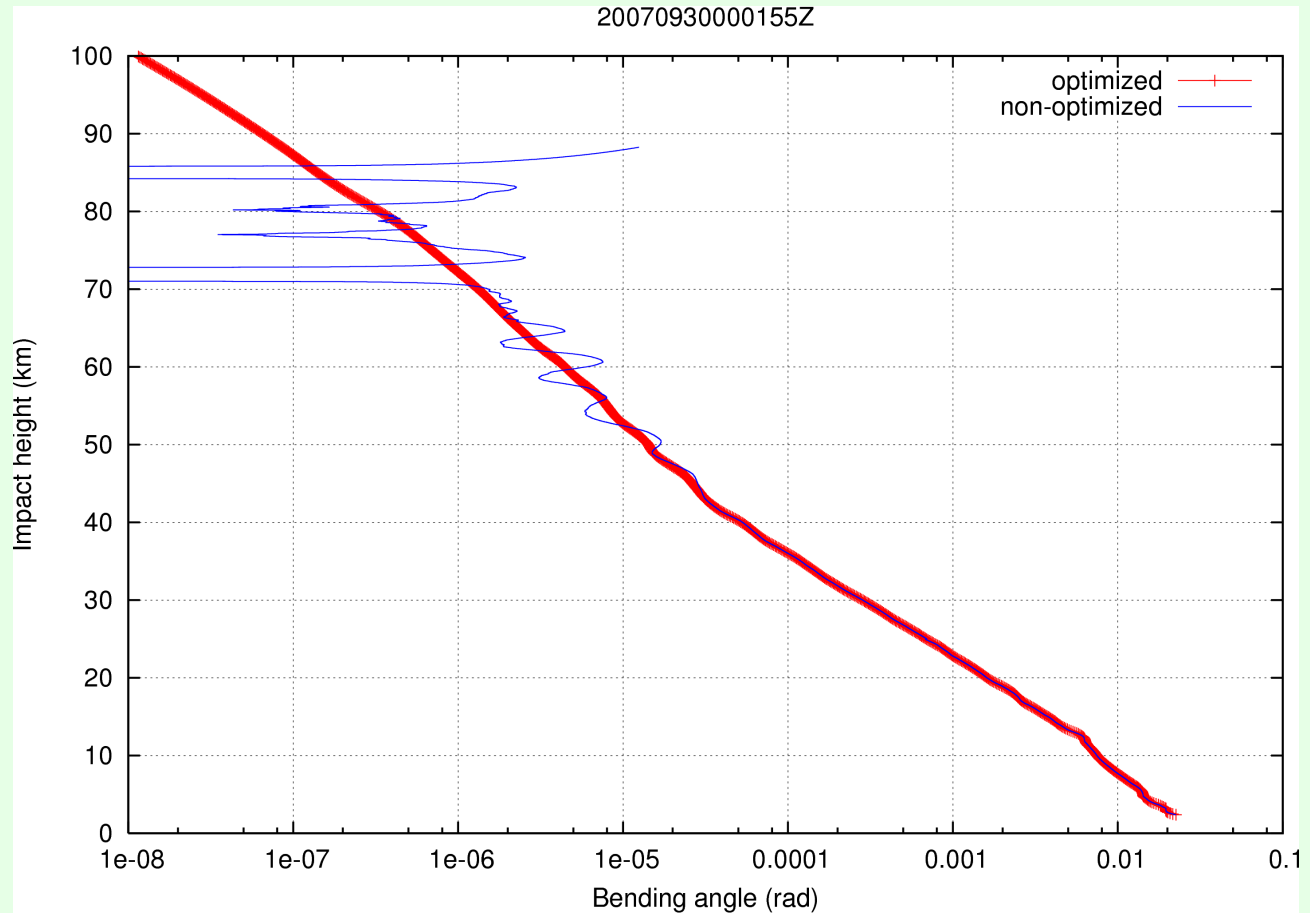
- integration by parts :  $\int_a^\infty \frac{\alpha(x) dx}{\sqrt{x^2 - a^2}} = - \int_a^\infty \ln\left(\frac{x}{a} + \sqrt{\left(\frac{x}{a}\right)^2 - 1}\right) \frac{d\alpha}{dx} dx$

- $x = \sqrt{s^2 + a^2} \Rightarrow \int_a^\infty \frac{\alpha(x) dx}{\sqrt{x^2 - a^2}} = \int_0^\infty \frac{\alpha(s) ds}{\sqrt{s^2 + a^2}}$

- $x = a \cosh \theta \Rightarrow \int_a^\infty \frac{\alpha(x) dx}{\sqrt{x^2 - a^2}} = \int_0^\infty \alpha(\theta) d\theta$

- ... and the one you use ...

# Example from GRAS data



# A closer look ...

